IN THE CLAIMS:

Delete claims 1-5 and replace with new claims 6-8 as shown in the attached Annexure A.

REMARKS

Item 3 of the Official Action has now been traversed.

Items 4, 7, 8, 9,10 are now moot in view of the new claim 6. The invention relates to deblurring images in the "Artcam" type camera disclosed in the priority documents referred to on page 2 of the specification, that is, a camera system with an inbuilt inkjet printer.

The Applicant has taken the opportunity to re-cast the specification into a more appropriate format and a substitute specification is attached. A marked up copy of the substitute specification is also attached. At the same time US patent application numbers of the co-pending, cross-referenced application have been added. These numbers were not available at the time of filing the present application as the co-pending applications were filed contemporaneously with the present application. Further, the change of the charts from landscape view to portrait view has been made purely to make it easier to read the specification.

The applicant respectively submits that no new matter has been added or claimed by the proposed amendments.

In view of the foregoing it is respectfully contended that all claims now pending in the above identified patent application recite a novel and not obvious system which is patentably distinguishable over the prior art. Accordingly, withdrawal of the outstanding rejection and the allowance of all claims now pending are respectfully requested and earnestly solicited.

CONCLUSION

It is respectfully submitted that all of the Examiner's objections have been successfully traversed. Accordingly, it is submitted that the application is now in condition for allowance. Reconsideration and allowance of the application is courteously solicited.

Very respectfully,

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Marked-up copy of substitute specification

TITLE OF INVENTION

"A DIGITAL CAMERA SYSTEM HAVING MOTION DEBLURRING MEANS"

INVENTOR:

Kia Silverbrook

CROSS REFERENCES TO RELATED APPLICATIONS

The following Australian provisional patent applications are hereby incorporated by cross-reference. For the purposes of location and identification, US patent applications identified by their US patent application serial numbers (USSN) are listed alongside the Australian applications from which the US patent applications claim the right of priority.

CROSS-REFERENCED AUSTRALIAN PROVISIONAL PATENT APPLICATION NO.	US PATENT/PATENT APPLICATION (CLAIMING RIGHT OF PRIORITY FROM AUSTRALIAN PROVISIONAL APPLICATION)	DOCKET NO.
PO7991	09/113,060	ART01
PO8505	09/113,070	ART02
PO7988	09/113,073	ART03
PO9395	09/112,748	ART04
PO8017	09/112,747	ART06
PO8014	09/112,776	ART07
PO8025	09/112,750	ART08
PO8032	09/112,746	ART09
PO7999	09/112,743	ART10
PO7998	09/112,742	ART11
PO8031	09/112,741	ART12
PO8030	6,196,541	ART13
PO7997	6,195,150	ART15
PO7979	09/113,053	ART16
PO8015	09/112,738	ART17
PO7978	09/113,067	ART18
PO7982	09/113,063	ART19
PO7989	09/113,069	ART20
PO8019	09/112,744	ART21
PO7980	09/113,058	ART22

CROSS-REFERENCED AUSTRALIAN PROVISIONAL PATENT APPLICATION NO.	US PATENT/PATENT APPLICATION (CLAIMING RIGHT OF PRIORITY FROM AUSTRALIAN PROVISIONAL APPLICATION)	DOCKET NO.
PO8018	09/112,777	ART24
PO7938	09/113,224	ART25
PO8016	09/112,804	ART26
PO8024	09/112,805	ART27
PO7940	09/113,072	ART28
PO7939	09/112,785	ART29
PO8501	6,137,500	ART30
PO8500	09/112,796	ART31
PO7987	09/113,071	ART32
PO8022	09/112,824	ART33
PO8497	09/113,090	ART34
PO8020	09/112,823	ART38
PO8023	09/113,222	ART39
PO8504	09/112,786	ART42
PO8000	09/113,051	ART43
PO7977	09/112,782	ART44
PO7934	09/113,056	ART45
PO7990	09/113,059	ART46
PO8499	09/113,091	ART47
PO8502	09/112,753	ART48
PO7981	09/113,055	ART50
PO7986	09/113,057	ART51
PO7983	09/113,054	ART52
PO8026	09/112,752	ART53
PO8027	09/112,759	ART54
PO8028	09/112,757	ART56
PO9394	09/112,758	ART57
PO9396	09/113,107	ART58
PO9397	09/112,829	ART59
PO9398	09/112,792	ART60
PO9399	6,106,147	ART61
PO9400	09/112,790	ART62
PO9401	09/112,789	ART63
PO9402	09/112,788	ART64
PO9403	09/112,795	ART65

CROSS-REFERENCED AUSTRALIAN PROVISIONAL PATENT APPLICATION NO.	US PATENT/PATENT APPLICATION (CLAIMING RIGHT OF PRIORITY FROM AUSTRALIAN PROVISIONAL APPLICATION)	DOCKET NO.
PO9405	09/112,749	ART66
PP0959	09/112,784	ART68
PP1397	6,217,165	ART69
PP2370	09/112,781	DOT01
PP2371	09/113,052	DOT02
PO8003	09/112,834	Fluid01
PO8005	09/113,103	Fluid02
PO9404	09/113,101	Fluid03
PO8066	6,227,652	IJ01
PO8072	6,213,588	IJ02
PO8040	6,213,589	IJ03
PO8071	6,231,163	IJ04
PO8047	6,247,795	IJ05
PO8035	09/113,099	IJ06
PO8044	6,244,691	IJ07
PO8063	6,257,704	IJ08
PO8057	09/112,778	IJ09
PO8056	6,220,694	IJ10
PO8069	6,257,705	IJ11
PO8049	6,247,794	IJ12
PO8036	6,234,610	IJ13
PO8048	6,247,793	IJ14
PO8070	6,264,306	IJ15
PO8067	6,241,342	IJ16
PO8001	6,247,792	IJ17
PO8038	6,264,307	IJ18
PO8033	6,254,220	IJ19
PO8002	6,234,611	IJ20
PO8068	09/112,808	IJ21
PO8062	09/112,809	IJ22
PO8034	6,239,821	IJ23
PO8039	09/113,083	IJ24
PO8041	6,247,796	IJ25
PO8004	09/113,122	IJ26
PO8037	09/112,793	IJ27

CROSS-REFERENCED AUSTRALIAN PROVISIONAL PATENT APPLICATION NO.	US PATENT/PATENT APPLICATION (CLAIMING RIGHT OF PRIORITY FROM AUSTRALIAN PROVISIONAL APPLICATION)	DOCKET NO.
PO8043	09/112,794	IJ28
PO8042	09/113,128	IJ29
PO8064	09/113,127	IJ30
PO9389	6,227,653	IJ31
PO9391	6,234,609	IJ32
PP0888	6,238,040	IJ33
PP0891	6,188,415	IJ34
PP0890	6,227,654	IJ35
PP0873	6,209,989	IJ36
PP0993	6,247,791	IJ37
PP0890	09/112,764	IJ38
PP1398	6,217,153	IJ39
PP2592	09/112,767	IJ40
PP2593	6,243,113	IJ41
PP3991	09/112,807	IJ42
PP3987	6,247,790	IJ43
PP3985	6,260,953	IJ44
PP3983	6,267,469	IJ45
PO7935	6,224,780	IJM01
PO7936	6,235,212	IJM02
PO7937	09/112,826	IJM03
PO8061	09/112,827	IJM04
PO8054	6,214,244	IJM05
PO8065	6,071,750	IJM06
PO8055	09/113,108	IJM07
PO8053	6,251,298	IJM08
PO8078	6,258,285	IJM09
PO7933	6,225,138	IJM10
PO7950	6,241,904	IJM11
PO7949	09/113,129	IJM12
PO8060	09/113,124	IJM13
PO8059	6,231,773	IJM14
PO8073	6,190,931	IJM15
PO8076	6,248,249	IJM16
PO8075	09/113,120	IJM17

CROSS-REFERENCED AUSTRALIAN PROVISIONAL PATENT APPLICATION NO.	US PATENT/PATENT APPLICATION (CLAIMING RIGHT OF PRIORITY FROM AUSTRALIAN PROVISIONAL APPLICATION)	DOCKET NO.
PO8079	6,241,906	IJM18
PO8050	09/113,116	IJM19
PO8052	6,241,905	IJM20
PO7948	09/113,117	IJM21
PO7951	6,231,772	IJM22
PO8074	09/113,130	IJM23
PO7941	09/113,110	IJM24
PO8077	6,248,248	IJM25
PO8058	09/113,087	IJM26
PO8051	09/113,074	IJM27
PO8045	6,110,754	IJM28
PO7952	09/113,088	IJM29
PO8046	09/112,771	IJM30
PO9390	6,264,849	IJM31
PO9392	6,254,793	IJM32
PP0889	6,235,211	IJM35
PP0887	09/112,801	IJM36
PP0882	6,264,850	IJM37
PP0874	6,258,284	IJM38
PP1396	09/113,098	IJM39
PP3989	6,228,668	IJM40
PP2591	6,180,427	IJM41
PP3990	6,171,875	IJM42
PP3986	09/112,830	IJM43
PP3984	6,245,247	IJM44
PP3982	09/112,835	IJM45
PP0895	6,231,148	IR01
PP0870	09/113,106	IR02
PP0869	09/113,105	IR04
PP0887	09/113,104	IR05
PP0885	6,238,033	IR06
PP0884	09/112,766	IR10
PP0886	6,238,111	IR12
PP0871	09/113,086	IR13
PP0876	09/113,094	IR14

CROSS-REFERENCED AUSTRALIAN PROVISIONAL PATENT APPLICATION NO.	US PATENT/PATENT APPLICATION (CLAIMING RIGHT OF PRIORITY FROM AUSTRALIAN PROVISIONAL APPLICATION)	DOCKET NO.
PP0877	09/112,760	IR16
PP0878	6,196,739	IR17
PP0879	09/112,774	IR18
PP0883	09/112,775	IR19
PP0880	6,152,619	IR20
PP0881	09/113,092	IR21
PO8006	6,087,638	MEMS02
PO8007	09/113,093	MEMS03
PO8008	09/113,062	MEMS04
PO8010	6,041,600	MEMS05
PO8011	09/113,082	MEMS06
PO7947	6,067,797	MEMS07
PO7944	09/113,080	MEMS09
PO7946	6,044,646	MEMS10
PO9393	09/113,065	MEMS11
PP0875	09/113,078	MEMS12
PP0894	09/113,075	MEMS13

STATEMENT REGARDING FEDERALLY SPONSORED RESEARCH OR DEVELOPMENT

Not applicable.

FIELD OF THE INVENTION

The present invention relates to digital image processing and in particular discloses A Camera System Having Motion Deblurring Means.

Further the present invention relates to the field of digital image cameras and in particular discloses a camera system having motion blur compensating means.

BACKGROUND OF THE INVENTION

Motion blur in the taking of images is a common significant problem. The motion blur normally occurs as a result of movement of the camera while taking the picture or otherwise as a result of movement of objects within an image.

As a result of motion blur, it is often the case that the image taken is non optimal.

SUMMARY OF THE INVENTION

It is an object of the present invention to provide a camera system having the ability to overcome the effects of motion blur.

In accordance with the first aspect of the present invention there is provided a camera system for outputting deblurred images, said system comprising;

an image sensor for sensing an image; a velocity detection means for determining any motion of said image relative to an external environment and to produce a velocity output indicative thereof; a processor means interconnected to said image sensor and said velocity detection means and adapted to process said sensed image utilising the velocity output so as to deblurr said image and to output said deblurred image.

Preferably, the camera system is connected to a printer means for immediate output of said deblurred image and is a portable handheld unit. The velocity detection means can comprise an accelerometer such as a micro-electro mechanical (MEMS) device.

BRIEF DESCRIPTION OF THE DRAWINGS

Notwithstanding any other forms which may fall within the scope of the present invention, preferred forms of the invention will now be described, by way of example only, with reference to the accompanying drawing in which:

Fig. 1 illustrates a schematic implementation of the preferred embodiment.

DESCRIPTION OF PREFERRED AND OTHER EMBODIMENTS

The preferred embodiment is preferably implemented through suitable programming of a hand held camera device such as that described in Australian Provisional Patent Application No. PO7991 filed 15 July, 1997 entitled "Image Processing Method and Apparatus (ART01)", in addition to Australian Provisional Patent Application entitled "Image Processing Method and Apparatus (ART01a)" filed concurrently herewith by the present applicant, the content of which is hereby

specifically incorporated by cross reference.

The aforementioned patent specifications disclose a camera system, hereinafter known as an "Artcam" type camera, wherein sensed images can be directly printed out by an internal Artcam portable camera unit. Further, the aforementioned specification discloses means and methods for performing various manipulations on images captured by the camera sensing device leading to the production of various effects in any output image. The manipulations are disclosed to be highly flexible in nature and can be implemented through the insertion into the Artcam of cards having encoded thereon various instructions for the manipulation of images, the cards hereinafter being known as "Artcards". The Artcam further has significant onboard processing power by an Artcam Central Processor unit (ACP) which is interconnected to a memory device for the storage of important data and images.

In the preferred embodiment, the Artcam device is modified so as to include a two dimensional motion sensor. The motion sensor can comprise a small micro-electro mechanical system (MEMS) device or other suitable device ~~leave~~ able to detect motion in two axes. The motion sensor can be mounted on the camera device and its output monitored by the Artcam central processor device which is disclosed in the afore-mentioned patent specifications.

Turning now to Fig. 1, there is illustrated a schematic of the preferred arrangement of the preferred embodiment. The accelerometer 1 outputs to the Artcam central processor 2 which also receives the blurred sensed image from the CCD device. The Artcam central processor 2 utilises the accelerometer readings so as to determine a likely angular velocity of the camera when the picture was taken. This velocity factor is then utilised by a suitably programmed Artcard processor 2 to apply a deblurring function to the blurred sensed image 3 thereby outputting a deblurred output image 4. The programming of the Artcard processor 2 so as to perform the deblurring can utilise standard algorithms known to those skilled in the art of computer programming and digital image restoration. For example, reference is made to the "Selected Papers on Digital Image Restoration", M. Ibrahim Sezan, Editor, SPIE Milestone series, volume 74, and in particular the reprinted paper at pages 167-175 thereof. Further, simplified techniques are shown in the "Image Processing Handbook", second edition, by John C. Russ, published by CRC Press at pages 336-341 thereof.

It would be therefore obvious to the person skilled in the art that many different techniques for motion blur removal can be utilised in the preferred embodiment. Additionally, other forms of motion sensors may be provided. Once the input image has been deblurred, the image is then

able to be printed out by the Artcam device in accordance with the techniques as discussed in the afore-mentioned patent specification.

It would be appreciated by a person skilled in the art that numerous variations and/or modifications may be made to the present invention as shown in the specific embodiment without departing from the spirit or scope of the invention as broadly described. The present embodiment is, therefore, to be considered in all respects to be illustrative and not restrictive.

Ink Jet Technologies

The embodiments of the invention use an ink jet printer type device. Of course many different devices could be used. However presently popular ink jet printing technologies are unlikely to be suitable.

The most significant problem with thermal ink jet is power consumption. This is approximately 100 times that required for high speed, and stems from the energy-inefficient means of drop ejection. This involves the rapid boiling of water to produce a vapor bubble which expels the ink. Water has a very high heat capacity, and must be superheated in thermal ink jet applications. This leads to an efficiency of around 0.02%, from electricity input to drop momentum (and increased surface area) out.

The most significant problem with piezoelectric ink jet is size and cost. Piezoelectric crystals have a very small deflection at reasonable drive voltages, and therefore require a large area for each nozzle. Also, each piezoelectric actuator must be connected to its drive circuit on a separate substrate. This is not a significant problem at the current limit of around 300 nozzles per print head, but is a major impediment to the fabrication of ~~pagewide~~ pagewidth print heads with 19,200 nozzles.

Ideally, the ink jet technologies used meet the stringent requirements of in-camera digital color printing and other high quality, high speed, low cost printing applications. To meet the requirements of digital photography, new ink jet technologies have been created. The target features include:

low power (less than 10 Watts)

high resolution capability (1,600 dpi or more)

photographic quality output

low manufacturing cost

small size (pagewidth times minimum cross section)

high speed (< 2 seconds per page).

All of these features can be met or exceeded by the ink jet systems described below with

Forty-five

differing levels of difficulty. ~~45~~ different ink jet technologies have been developed by the Assignee to give a wide range of choices for high volume manufacture. These technologies form part of separate applications assigned to the present Assignee as set out in the table ~~below~~ under the heading Cross References to Related Applications.

The ink jet designs shown here are suitable for a wide range of digital printing systems, from battery powered one-time use digital cameras, through to desktop and network printers, and through to commercial printing systems.

For ease of manufacture using standard process equipment, the print head is designed to be a monolithic 0.5 micron CMOS chip with MEMS post processing. For color photographic applications, the print head is 100 mm long, with a width which depends upon the ink jet type. The smallest print head designed is IJ38, which is 0.35 mm wide, giving a chip area of 35 square mm. The print heads each contain 19,200 nozzles plus data and control circuitry.

Ink is supplied to the back of the print head by injection molded plastic ink channels. The molding requires 50 micron features, which can be created using a lithographically micromachined insert in a standard injection molding tool. Ink flows through holes etched through the wafer to the nozzle chambers fabricated on the front surface of the wafer. The print head is connected to the camera circuitry by tape automated bonding.

Tables of Drop-on-Demand Ink Jets

Eleven important characteristics of the fundamental operation of individual ink jet nozzles have been identified. These characteristics are largely orthogonal, and so can be elucidated as an eleven dimensional matrix. Most of the eleven axes of this matrix include entries developed by the present assignee.

The following tables form the axes of an eleven dimensional table of ink jet types.

Actuator mechanism (18 types)

Basic operation mode (7 types)

Auxiliary mechanism (8 types)

Actuator amplification or modification method (17 types)

Actuator motion (19 types)

Nozzle refill method (4 types)

Method of restricting back-flow through inlet (10 types)

Nozzle clearing method (9 types)

Nozzle plate construction (9 types)

Drop ejection direction (5 types)

Ink type (7 types)

The complete eleven dimensional table represented by these axes contains 36.9 billion possible configurations of ink jet nozzle. While not all of the possible combinations result in a viable ink jet technology, many million configurations are viable. It is clearly impractical to elucidate all of the possible configurations. Instead, certain ink jet types have been investigated in detail. These are designated IJ01 to IJ45 above ~~above~~ which match the datasheet numbers in the table under the heading Cross References to Related Applications.

Other ink jet configurations can readily be derived from these ~~45~~ forty-five examples by substituting alternative configurations along one or more of the 11 axes. Most of the IJ01 to IJ45 examples can be made into ink jet print heads with characteristics superior to any currently available ink jet technology.

Where there are prior art examples known to the inventor, one or more of these examples are listed in the examples column of the tables below. The IJ01 to IJ45 series are also listed in the examples column. In some cases, a ~~printer~~ print technology may be listed more than once in a table, where it shares characteristics with more than one entry.

Suitable applications for the ink jet technologies include: Home printers, Office network printers, Short run digital printers, Commercial print systems, Fabric printers, Pocket printers, Internet WWW printers, Video printers, Medical imaging, Wide format printers, Notebook PC printers, Fax machines, Industrial printing systems, Photocopiers, Photographic minilabs etc.

The information associated with the aforementioned 11 dimensional matrix are set out in the following tables.

Orientation of the sheets has been changed from landscape to portrait

ACTUATOR MECHANISM (APPLIED ONLY TO SELECTED INK DROPS)				
	Description	**Advantages**	**Disadvantages**	**Examples**
Thermal bubble	An electrothermal heater heats the ink to above boiling point, transferring significant heat to the aqueous ink. A bubble nucleates and quickly forms, expelling the ink. The efficiency of the process is low, with typically less than 0.05% of the electrical energy being transformed into kinetic energy of the drop.	◆ Large force generated ◆ Simple construction ◆ No moving parts ◆ Fast operation ◆ Small chip area required for actuator	◆ High power ◆ Ink carrier limited to water ◆ Low efficiency ◆ High temperatures required ◆ High mechanical stress ◆ Unusual materials required ◆ Large drive transistors ◆ Cavitation causes actuator failure ◆ Kogation reduces bubble formation ◆ Large print heads are difficult to fabricate	◆ Canon Bubblejet 1979 Endo et al GB patent 2,007,162 ◆ Xerox heater-in-pit 1990 Hawkins et al USP 4,899,181 ◆ Hewlett-Packard TIJ 1982 Vaught et al USP 4,490,728
Piezo-electric	A piezoelectric crystal such as lead lanthanum zirconate (PZT) is electrically activated, and either expands, shears, or bends to apply pressure to the ink, ejecting drops.	◆ Low power consumption ◆ Many ink types can be used ◆ Fast operation ◆ High efficiency	◆ Very large area required for actuator ◆ Difficult to integrate with electronics ◆ High voltage drive transistors required ◆ Full pagewidth print heads impractical due to actuator size ◆ Requires electrical poling in high field strengths during manufacture	◆ Kyser et al USP 3,946,398 ◆ Zoltan USP 3,683,212 ◆ 1973 Stemme USP 3,747,120 ◆ Epson Stylus ◆ Tektronix ◆ IJ04